

# Približek tesne vezi: p-pasovi v kubičnih kristalih

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## 1.) Naloga (Ashcroft, 2.naloga v 10.poglavju, str.189)

V kubičnem kristalu imajo funkcije, ki opisujejo trojno degeneracijo p-pasov obliko  $x\phi(r)$ ,  $y\phi(r)$  in  $z\phi(r)$ , kjer je funkcija  $\phi(r)$  odvisna le od velikosti vektorja  $\vec{r}$ .

Energijo treh p-pasov dobimo iz

$$(\varepsilon(\vec{k}) - E_p)\delta_{ij} + \beta_{ij} + \tilde{\gamma}_{ij}(\vec{k}) = 0,$$

kjer je

$$\tilde{\gamma}_{ij}(\vec{k}) = \sum_{\vec{R}} e^{i\vec{k}\cdot\vec{R}} \gamma_{ij}(\vec{R}),$$

$$\gamma_{ij}(\vec{R}) = - \int d\vec{r} \psi_i^*(\vec{r}) \psi_j(\vec{r} - \vec{R}) \Delta U(\vec{r}),$$

$$\beta_{ij} = \gamma_{ij}(\vec{R} = 0)$$

in  $\varepsilon(\vec{k})$  Blochova energija.

### a) Pokaži, da zaradi kubične simetrije velja

$$\beta_{xx} = \beta_{yy} = \beta_{zz} = \beta,$$

$$\beta_{xy} = 0.$$

b) Privzamimo, da je  $\gamma_{ij}(\vec{R})$  zanemarljiv razen za najbližje sosede  $\vec{R}$ . Pokaži, da je za preprosto kubično mrežo  $\tilde{\gamma}_{ij}(\vec{k})$  diagonalen, tako da  $x\phi(r)$ ,  $y\phi(r)$  in  $z\phi(r)$  generirajo neodvisne pasove.

c) Za fcc Bravaisovo mrežo, kjer v  $\gamma_{ij}(\vec{R})$  upoštevamo le prvega najbližjega soseda, pokaži, da so energijski pasovi koreni spodnje enačbe

$$\begin{bmatrix} \varepsilon(\vec{k}) - \varepsilon^0(\vec{k}) + 4\gamma_0 \cos(\frac{1}{2}k_y a) \cos(\frac{1}{2}k_z a) & -4\gamma_1 \sin(\frac{1}{2}k_x a) \sin(\frac{1}{2}k_y a) & -4\gamma_1 \sin(\frac{1}{2}k_x a) \sin(\frac{1}{2}k_z a) \\ -4\gamma_1 \sin(\frac{1}{2}k_y a) \sin(\frac{1}{2}k_x a) & \varepsilon(\vec{k}) - \varepsilon^0(\vec{k}) + 4\gamma_0 \cos(\frac{1}{2}k_y a) \cos(\frac{1}{2}k_z a) & -4\gamma_1 \sin(\frac{1}{2}k_y a) \sin(\frac{1}{2}k_z a) \\ -4\gamma_1 \sin(\frac{1}{2}k_z a) \sin(\frac{1}{2}k_x a) & -4\gamma_1 \sin(\frac{1}{2}k_z a) \sin(\frac{1}{2}k_y a) & \varepsilon(\vec{k}) - \varepsilon^0(\vec{k}) + 4\gamma_0 \cos(\frac{1}{2}k_x a) \cos(\frac{1}{2}k_y a) \end{bmatrix} = 0$$

Vpeljali smo

$$\begin{aligned} \varepsilon^0(\vec{k}) &= E_p - \beta - 4\gamma_2 [\cos(\frac{1}{2}k_x a) \cos(\frac{1}{2}k_z a) + \cos(\frac{1}{2}k_x a) \cos(\frac{1}{2}k_y a) + \cos(\frac{1}{2}k_y a) \cos(\frac{1}{2}k_z a)], \\ \gamma_0 &= - \int d\vec{r} [x^2 - y(y - \frac{1}{2}a)] \phi(r) \phi([x^2 + (y - \frac{1}{2}a)^2 + (z - \frac{1}{2}a)^2]^{1/2}) \Delta U(\vec{r}), \\ \gamma_1 &= - \int d\vec{r} [x(y - \frac{1}{2}a)] \phi(r) \phi([(x - \frac{1}{2}a)^2 + (y - \frac{1}{2}a)^2 + z^2]^{1/2}) \Delta U(\vec{r}), \\ \gamma_2 &= - \int d\vec{r} x(x - \frac{1}{2}a) \phi(r) \phi([(x - \frac{1}{2}a)^2 + (y - \frac{1}{2}a)^2 + z^2]^{1/2}) \Delta U(\vec{r}). \end{aligned}$$

d) Pokaži, da so pri  $\vec{k}=0$  vsi trije pasovi degenerirani, ko imamo  $\vec{k}$  v smeri kubične osi ( $\Gamma X$ ) ali diagonale ( $\Gamma L$ ) pa imamo dvojno degeneracijo.

## 2.) Rešitev

a) Želimo poznati  $\beta_{xx} = \beta_{yy} = \beta_{zz} = \beta$  in  $\beta_{xy} = 0$ .

Zapišemo

$$\beta_{xx} = - \int d\vec{r} \psi_x^*(\vec{r}) \cdot \psi_x \Delta U(\vec{r}) = - \int d\vec{r} \cdot x^2 \cdot |\phi(\vec{r})|^2 \cdot \Delta U(\vec{r})$$

in

$$\beta_{yy} = - \int d\vec{r} \psi_y^*(\vec{r}) \cdot \psi_y \Delta U(\vec{r}) = - \int d\vec{r} \cdot y^2 \cdot |\phi(\vec{r})|^2 \cdot \Delta U(\vec{r})$$

Sedaj enačbi odštejemo  $0 = \beta_{xx} - \beta_{yy} = - \int d\vec{r} \cdot (x^2 - y^2) \cdot |\phi(\vec{r})|^2 \cdot \Delta U(\vec{r})$  ter uvedemo novi spremenljivki  $x' = x - y$  in  $y' = x + y$ , kar je v bistvu rotacija v prostoru.

Dobimo

$$0 = \beta_{xx} - \beta_{yy} = - \int d\vec{r} \cdot (x' \cdot y') \cdot |\phi(\vec{r}')|^2 \cdot \Delta U(\vec{r}') = \beta_{xy} = 0.$$

- b) Upoštevati moramo le najbližje sosede  $\vec{R}$ . Teh sosedov je 6, in sicer  
 $\vec{R} = a(\pm 1, 0, 0); a(0, 0, \pm 1); a(0, \pm 1, 0)$ .

Pokazati želimo, da so izvendiagonalni elementi  $\tilde{\gamma}_{ij}(\vec{k})$  enaki 0.

$$\begin{aligned}\tilde{\gamma}_{xy}(\vec{k}) = & -e^{ik_x a} \int d\vec{r} \cdot xy \cdot \phi(\vec{r}) \cdot \phi\left(\left((x-a)^2 + y^2 + z^2\right)^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\ & -e^{-ik_x a} \int d\vec{r} \cdot xy \cdot \phi(\vec{r}) \cdot \phi\left(\left((x+a)^2 + y^2 + z^2\right)^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\ & -e^{ik_y a} \int d\vec{r} \cdot x(y-a) \cdot \phi(\vec{r}) \cdot \phi\left(\left(x^2 + (y-a)^2 + z^2\right)^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\ & -e^{-ik_y a} \int d\vec{r} \cdot x(y+a) \cdot \phi(\vec{r}) \cdot \phi\left(\left(x^2 + (y+a)^2 + z^2\right)^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\ & -e^{ik_z a} \int d\vec{r} \cdot xy \cdot \phi(\vec{r}) \cdot \phi\left(\left(x^2 + y^2 + (z-a)^2\right)^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\ & -e^{-ik_z a} \int d\vec{r} \cdot xy \cdot \phi(\vec{r}) \cdot \phi\left(\left(x^2 + y^2 + (z+a)^2\right)^{\frac{1}{2}}\right) \Delta U(\vec{r}) = 0\end{aligned}$$

saj zaradi rotacijske transformacije  $x \rightarrow y$  in  $y \rightarrow -x$  vsak integral zamenja predznak.

- c) Energijo dobimo, če postavimo determinant enako nič:

$$|(\varepsilon(\vec{k}) - E_p)\delta_{ij} + \beta_{ij} + \tilde{\gamma}_{ij}(\vec{k})| = 0$$

Najprej bomo pokazali, da velja

$$\varepsilon(\vec{k}) - E_p + \beta_{xx} + \tilde{\gamma}_{xx}(\vec{k}) = \varepsilon(\vec{k}) - \varepsilon^0(\vec{k}) + 4\gamma_0 \cos\left(\frac{1}{2}k_y a\right) \cos\left(\frac{1}{2}k_z a\right)$$

V približku tesnih vezi upoštevamo le najbližje sosede glede na izhodišče (teh je 12)

$$\vec{R} = a(\pm 1, \pm 1, 0); a(\pm 1, 0, \pm 1); a(0, \pm 1, \pm 1)$$

V tem približku bomo izračunali  $\tilde{\gamma}_{xx}(\vec{k})$ .

$$\begin{aligned}
\tilde{V}_{xx}(\vec{k}) &= \sum_R e^{i\vec{k}\cdot\vec{R}} = \\
&-e^{i\frac{a}{2}(k_x+k_y)} \int d\vec{r} \cdot x \left(x - \frac{a}{2}\right) \cdot \phi(\vec{r}) \cdot \phi\left(\left[\left(x - \frac{a}{2}\right)^2 + \left(y - \frac{a}{2}\right)^2 + z^2\right]^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\
&-e^{i\frac{a}{2}(k_x-k_y)} \int d\vec{r} \cdot x \left(x - \frac{a}{2}\right) \cdot \phi(\vec{r}) \cdot \phi\left(\left[\left(x - \frac{a}{2}\right)^2 + \left(y + \frac{a}{2}\right)^2 + z^2\right]^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\
&-e^{i\frac{a}{2}(-k_x+k_y)} \int d\vec{r} \cdot x \left(x + \frac{a}{2}\right) \cdot \phi(\vec{r}) \cdot \phi\left(\left[\left(x + \frac{a}{2}\right)^2 + \left(y - \frac{a}{2}\right)^2 + z^2\right]^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\
&-e^{i\frac{a}{2}(-k_x-k_y)} \int d\vec{r} \cdot x \left(x + \frac{a}{2}\right) \cdot \phi(\vec{r}) \cdot \phi\left(\left[\left(x + \frac{a}{2}\right)^2 + \left(y + \frac{a}{2}\right)^2 + z^2\right]^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\
&-e^{i\frac{a}{2}(k_x+k_z)} \int d\vec{r} \cdot x \left(x - \frac{a}{2}\right) \cdot \phi(\vec{r}) \cdot \phi\left(\left[\left(x - \frac{a}{2}\right)^2 + y^2 + \left(z - \frac{a}{2}\right)^2\right]^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\
&-e^{i\frac{a}{2}(k_x-k_z)} \int d\vec{r} \cdot x \left(x - \frac{a}{2}\right) \cdot \phi(\vec{r}) \cdot \phi\left(\left[\left(x - \frac{a}{2}\right)^2 + y^2 + \left(z + \frac{a}{2}\right)^2\right]^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\
&-e^{i\frac{a}{2}(-k_x+k_z)} \int d\vec{r} \cdot x \left(x + \frac{a}{2}\right) \cdot \phi(\vec{r}) \cdot \phi\left(\left[\left(x + \frac{a}{2}\right)^2 + y^2 + \left(z - \frac{a}{2}\right)^2\right]^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\
&-e^{i\frac{a}{2}(-k_x-k_z)} \int d\vec{r} \cdot x \left(x + \frac{a}{2}\right) \cdot \phi(\vec{r}) \cdot \phi\left(\left[\left(x + \frac{a}{2}\right)^2 + y^2 + \left(z + \frac{a}{2}\right)^2\right]^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\
&-e^{i\frac{a}{2}(k_y+k_z)} \int d\vec{r} \cdot x^2 \cdot \phi(\vec{r}) \cdot \phi\left(\left[x^2 + \left(y - \frac{a}{2}\right)^2 + \left(z - \frac{a}{2}\right)^2\right]^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\
&-e^{i\frac{a}{2}(k_y-k_z)} \int d\vec{r} \cdot x^2 \cdot \phi(\vec{r}) \cdot \phi\left(\left[x^2 + \left(y - \frac{a}{2}\right)^2 + \left(z + \frac{a}{2}\right)^2\right]^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\
&-e^{i\frac{a}{2}(-k_y+k_z)} \int d\vec{r} \cdot x^2 \cdot \phi(\vec{r}) \cdot \phi\left(\left[x^2 + \left(y + \frac{a}{2}\right)^2 + \left(z - \frac{a}{2}\right)^2\right]^{\frac{1}{2}}\right) \Delta U(\vec{r}) \\
&-e^{i\frac{a}{2}(-k_y-k_z)} \int d\vec{r} \cdot x^2 \cdot \phi(\vec{r}) \cdot \phi\left(\left[x^2 + \left(y + \frac{a}{2}\right)^2 + \left(z + \frac{a}{2}\right)^2\right]^{\frac{1}{2}}\right) \Delta U(\vec{r})
\end{aligned}$$

Opazimo

$$\begin{aligned}
 & - \int d\vec{r} \cdot x \left(x - \frac{a}{2}\right) \cdot \phi(\vec{r}) \cdot \phi \left( \left[ \left(x - \frac{a}{2}\right)^2 + \left(y - \frac{a}{2}\right)^2 + z^2 \right]^{\frac{1}{2}} \right) \Delta U(\vec{r}) = \gamma_2 \\
 & - \int d\vec{r} \cdot x^2 \cdot \phi(\vec{r}) \cdot \phi \left( \left[ x^2 + \left(y + \frac{a}{2}\right)^2 + \left(z + \frac{a}{2}\right)^2 \right]^{\frac{1}{2}} \right) \Delta U(\vec{r}) = \gamma_0 + \gamma_2
 \end{aligned}$$

Torej lahko zgornjo enačbo prepišemo v

$$\begin{aligned}
 \tilde{\gamma}_{xx}(\vec{k}) = & \left( e^{i\frac{a}{2}(k_x+k_y)} + e^{i\frac{a}{2}(k_x-k_y)} + e^{-i\frac{a}{2}(k_x+k_y)} + e^{-i\frac{a}{2}(k_x-k_y)} + \right. \\
 & \left. + e^{i\frac{a}{2}(k_x+k_z)} + e^{i\frac{a}{2}(k_x-k_z)} + e^{-i\frac{a}{2}(k_x+k_z)} + e^{-i\frac{a}{2}(k_x-k_z)} \right) \gamma_2 \\
 & + \left( e^{i\frac{a}{2}(k_y+k_z)} + e^{i\frac{a}{2}(k_y-k_z)} + e^{-i\frac{a}{2}(k_y+k_z)} + e^{-i\frac{a}{2}(k_y-k_z)} \right) (\gamma_0 + \gamma_2)
 \end{aligned}$$

oziroma

$$\begin{aligned}
 \tilde{\gamma}_{xx}(\vec{k}) = & \left( 4 \cos\left(\frac{1}{2}k_x a\right) \cos\left(\frac{1}{2}k_y a\right) + 4 \cos\left(\frac{1}{2}k_x a\right) \cos\left(\frac{1}{2}k_z a\right) \right) \gamma_2 \\
 & + 4 \cos\left(\frac{1}{2}k_y a\right) \cos\left(\frac{1}{2}k_z a\right) (\gamma_0 + \gamma_2)
 \end{aligned}$$

Sedaj lahko  $\tilde{\gamma}_{xx}(\vec{k})$  vstavimo v začetno enačbo in z malo računanja dobimo

$$\varepsilon(\vec{k}) - E_p + \beta_{xx} + \tilde{\gamma}_{xx}(\vec{k}) = \varepsilon(\vec{k}) - \varepsilon^0(\vec{k}) + 4\gamma_0 \cos\left(\frac{1}{2}k_y a\right) \cos\left(\frac{1}{2}k_z a\right)$$

kar smo hoteli pokazati. Ostale elemente dobimo na podoben način.

**d)** Za  $\vec{k}=0$  so vsi trije pasovi degenerirani

$$\varepsilon_0 = E_p - \beta - 12\gamma_2 - 4\gamma_0 \rightarrow E_p - \beta = \varepsilon_0 + 12\gamma_2 + 4\gamma_0$$

Za  $\vec{k}$  v smeri osi x dobimo  $\Gamma X - \vec{k} = \left(\frac{2\pi\mu}{a}, 0, 0\right)$ , kjer  $0 \leq \mu \leq 1$ .

$$\frac{e_1(\mu)}{e_0} = 1 + \frac{8\gamma_2}{e_0} (1 - \cos(\pi \cdot \mu))$$

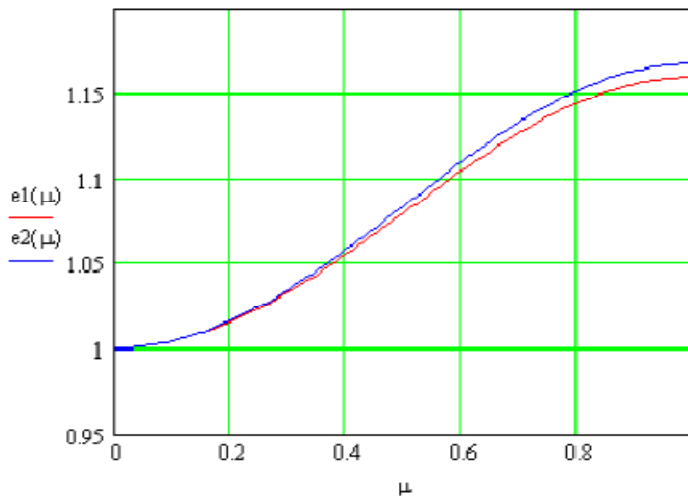
in

$$\frac{e_2(\mu)}{e_0} = 1 + \frac{8\gamma_2 + 4\gamma_0}{e_0} (1 - \cos(\pi \cdot \mu))$$

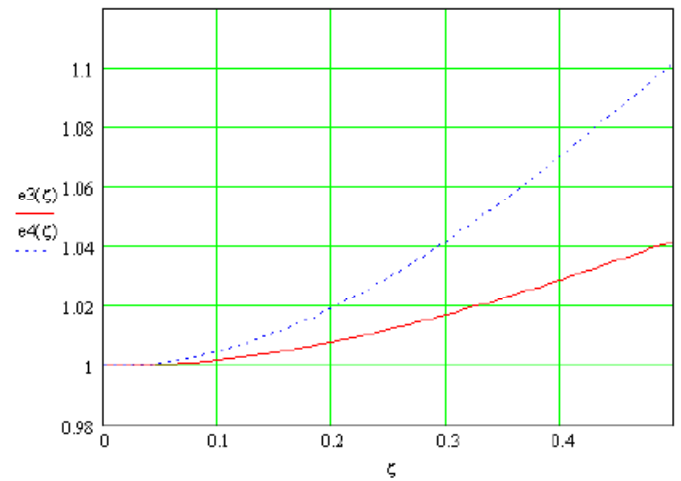
Za  $\vec{k}$  v smeri diagonale :  $\Gamma L - \vec{k} = \frac{2\pi}{a} (\xi, \xi, \xi)$ , kjer  $0 \leq \xi \leq \frac{1}{2}$ .

$$\frac{e_1(\xi)}{e_0} = 1 + \frac{12\gamma_2 + 4\gamma_0 - 4\gamma_1}{e_0} \sin^2(\pi \cdot \xi)$$

$$\frac{e_2(\xi)}{e_0} = 1 + \frac{12\gamma_2 + 4\gamma_0 + 8\gamma_1}{e_0} \sin^2(\pi \cdot \xi)$$



Slika 1: Degeneracija;  $\vec{k}$  v smeri osi x ( $\Gamma X$ )



Slika 2: Degeneracija;  $\vec{k}$  v smeri diagonale