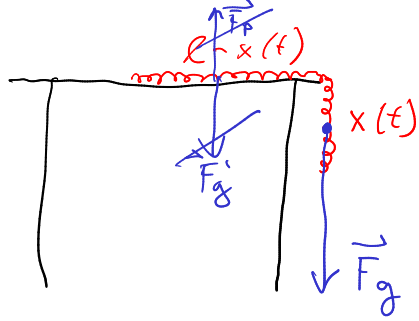
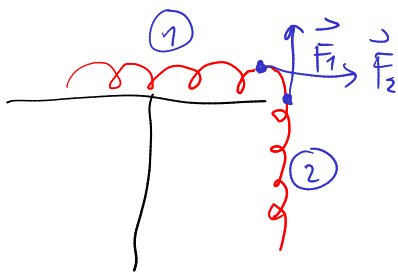


3.9



$l, m$   
 $x(t) = ?$        $x(0) = x_0$

$$F_g = m(t) \cdot g = m \frac{x(t)}{l} g$$



$$|\vec{F}_1| = |\vec{F}_2| = F$$

$$\textcircled{1} F_2 = m \frac{l - x(t)}{l} a$$

$$\textcircled{2} m \frac{x(t)}{l} g - F_1 = m \frac{x(t)}{l} a$$

$$\Sigma: \frac{m x(t)}{l} g = m a = m x''(t)$$

$$x''(t) = \frac{g}{l} x(t)$$

navadna linearna diferencialna enaiba drugego reda

$$x(t) = A f_1(t) + B f_2(t)$$

$$x(t) = A e^{\sqrt{\frac{g}{l}} t} + B e^{-\sqrt{\frac{g}{l}} t}$$

$$x''(t) = x(t)$$

$$e^t$$

$$e^{-t}$$

2. zacetna pogoja:  $x(0) = x_0$   
 $x'(0) = 0$

$$x(0) = A + B = x_0$$

$$x'(0) = \left( A \sqrt{\frac{g}{l}} e^{\sqrt{\frac{g}{l}} t} + B \left( -\sqrt{\frac{g}{l}} \right) e^{-\sqrt{\frac{g}{l}} t} \right) \Big|_{t=0}$$

$$= \sqrt{\frac{g}{l}} (A - B) = 0$$

$$\hookrightarrow A = B$$

$$\hookrightarrow A = B = \frac{x_0}{2}$$

$$\rightarrow x(t) = \frac{x_0}{2} (e^{\sqrt{\frac{g}{l}} t} + e^{-\sqrt{\frac{g}{l}} t})$$

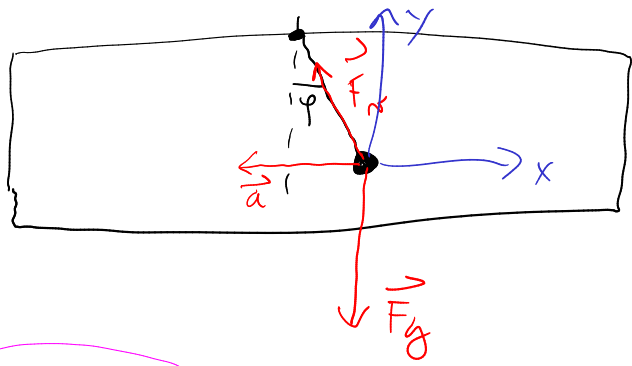
$$x(t) = x_0 \cosh \sqrt{\frac{g}{l}} t$$

3.51

$$a = 0.7 \text{ m/s}^2$$

$$l = 1 \text{ m}$$

$$f = ?$$



1.)

$$\sum \vec{F} = m\vec{a}$$

$$\vec{F}_g + \vec{F}_v = m\vec{a}$$

$$x: 0 - F_v \sin \varphi = -ma \rightarrow F_v \sin \varphi = ma$$

$$y: -mg + F_v \cos \varphi = 0 \rightarrow F_v \cos \varphi = mg$$

$$\therefore \tan \varphi = \frac{a}{g}$$

$$\varphi = \arctan \frac{a}{g} = 4^\circ$$

2.) s sistemskimi silami

$$\sum \vec{F} + \vec{F}_s = 0$$

$$\sum \vec{F} - m\vec{a} = 0$$

3.52

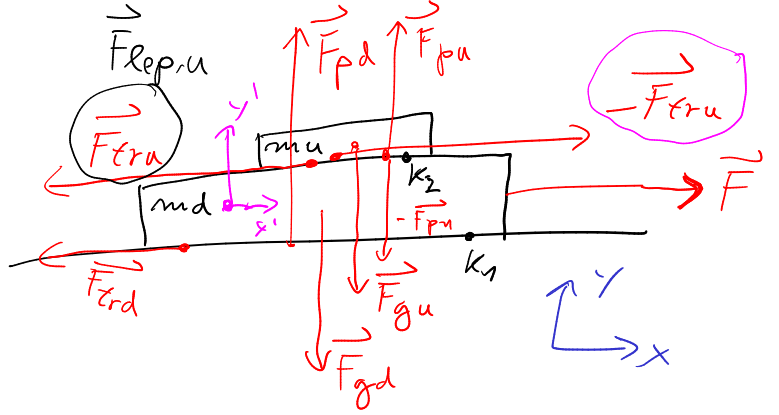
$m_D = 2 \text{ kg}$

$m_u = 1 \text{ kg}$

$k_1 = 0.4$

$k_2 = 0.3$

$F_{\text{min}} = ?$



1.) sistem deska + utež:

$$\vec{F}_{pd} + \vec{F}_{gd} + \vec{F}_{gu} + \vec{F} + \vec{F}_{erd} = (m_D + m_u) \vec{a}$$

x:  $-F_{erd} = (m_D + m_u) a$

y:  $-m_D g - m_u g + F_{pd} = 0$

$F_{erd} = F_{pd} \cdot k_1$

$F_{erd} = (m_D + m_u) g k_1$

$F - (m_D + m_u) g k_1 = (m_D + m_u) a$

$a = -g k_1 + \frac{F_{\text{min}}}{m_D + m_u}$

2.) u posrešenem koordinatnem sistemu

drugi Newtonov zakon za utež:

$\vec{F}_{pu} + \vec{F}_{gu} - \vec{F}_{ru} - m_u \vec{a} = 0$   
sistemsko sila

x':  $F_{ru} - m_u a = 0$

y':  $F_{pu} - m_u g = 0$

$F_{ru} = F_{pu} \cdot k_2$

$F_{ru} = m_u g k_2$

$m_u g k_2 - m_u a = 0$

$a = g k_2$

$F_{ep,u} \leq F_{pu} \cdot k_2$

↳ posredek, pri kateri utež zdrsu, ker je sila lepenga na mostu več obdržati na deski

$g k_2 = -g k_1 + \frac{F_{\text{min}}}{m_D + m_u}$

$F_{\text{min}} = (m_D + m_u) \cdot g (k_1 + k_2) = 3 \text{ kg} \cdot 10 \frac{\text{m}}{\text{s}^2} \cdot 0.7 = \underline{\underline{21 \text{ N}}}$

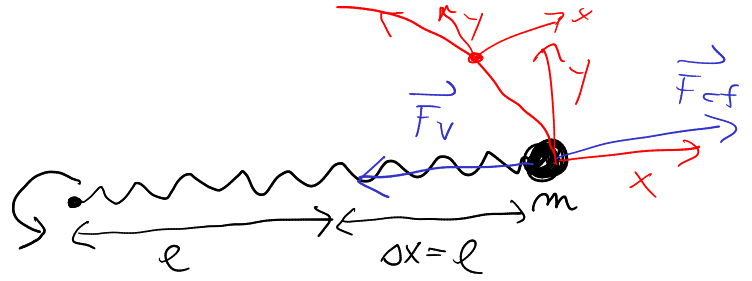
3.56

$$k = 20 \frac{\text{N}}{\text{cm}}$$

$$m = 100 \text{g}$$

$$\frac{\Delta x = l}{v}$$

v



bree systeemlich sil

$$\sum \vec{F} = m \vec{a}$$

$$\vec{F}_v = m \vec{a}_R$$

$$a_R = R \omega^2$$

$$F_v = m R \omega^2$$

$$\sum \vec{F} + \vec{F}_s = 0$$

$$\vec{F}_v + \vec{F}_{cf} = 0$$

$$F_v = F_{cf}$$

$$k \Delta x = m R \omega^2$$

$$k l = m (2l) (2\pi v)^2$$

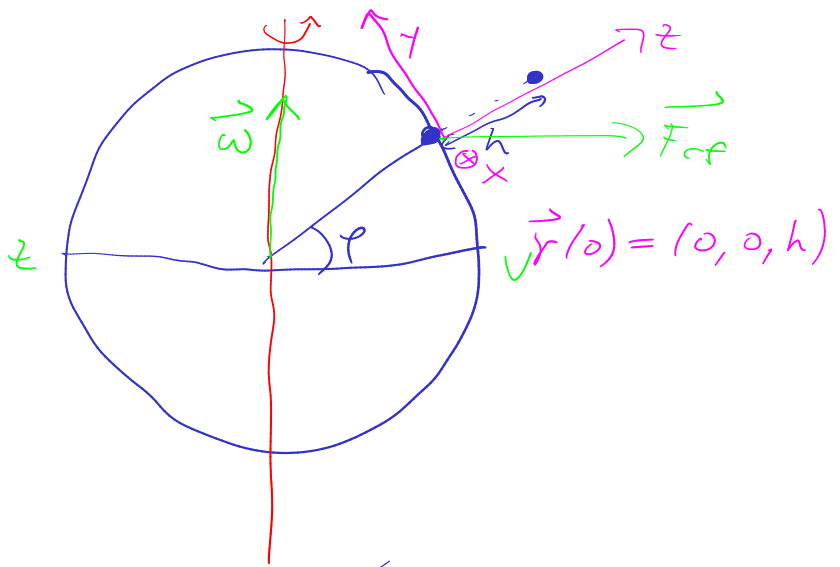
$$2\pi v = \sqrt{\frac{k}{2m}}$$

$$v = \frac{1}{2\pi} \sqrt{\frac{k}{2m}} = \frac{1}{2\pi} \sqrt{\frac{20 \text{N}}{0.01 \text{m} \cdot 2 \cdot 0.1 \text{kg}}}$$

$$= 15,9 \frac{1}{\text{s}} = 15,9 \text{ Hz}$$

$$N = \frac{k \cdot m}{s^2}$$

3.66  $\varphi = 30^\circ$   
 $h = 125 \text{ m}$   
 $\Delta x = ?$



$$\sum \vec{F} - m \vec{\omega} \times (\vec{\omega} \times \vec{r}) - 2m \vec{\omega} \times \vec{v} = m \vec{a}$$

$\vec{F}_g$       ~~centrifugalna sila~~      Coriolisova sila  
 zanemarimo

1) prosti pad:  $z(t) = h - \frac{g t^2}{2}$   
 $v_z(t) = z'(t) = -g t$        $\vec{v} = \begin{pmatrix} 0 \\ 0 \\ -g t \end{pmatrix}$

2.) popravak zaradi Coriolisove sile:

$$\vec{F}_c = -2m \vec{\omega} \times \vec{v} \quad \vec{\omega} = \begin{pmatrix} 0 \\ \omega \cos \varphi \\ \omega \sin \varphi \end{pmatrix}$$

$$\vec{F}_c = -2m \begin{pmatrix} \omega \cos \varphi \cdot (-g t) \\ \dots \\ \dots \end{pmatrix}$$

$$F_{cx} = 2m \omega \cos \varphi g t = m a_x$$

$$a_x = 2 \omega \cos \varphi g t$$

$$v_x = \int_0^t a_x dt' = 2 \omega \cos \varphi g \frac{t^2}{2}$$

$$x(t) = \int_0^t v_x dt' = \omega \cos \varphi g \frac{t^3}{3}$$

$$z(t) = h - \frac{g t^2}{2}$$

$$z(t) = 0 = h - \frac{g t^2}{2}$$

$$t = \sqrt{\frac{2h}{g}}$$

↑ čas, ko pride kamen na fla

$$\Delta x = \frac{\omega \cos \varphi g}{3} \left( \frac{2h}{g} \right)^{3/2}$$

$$\Delta x = \frac{1}{3} \omega \cos \varphi \sqrt{\frac{8h^3}{g}}$$

$$\Delta x = \frac{1}{3} \frac{2\pi}{24 \cdot 3600 \text{ s}} \cos 30^\circ \sqrt{\frac{8 \cdot (125 \text{ m})^3}{9.81 \text{ m/s}^2}} = 2,6 \text{ cm}$$

5.2

$$v_0 = 5 \text{ m/s}$$

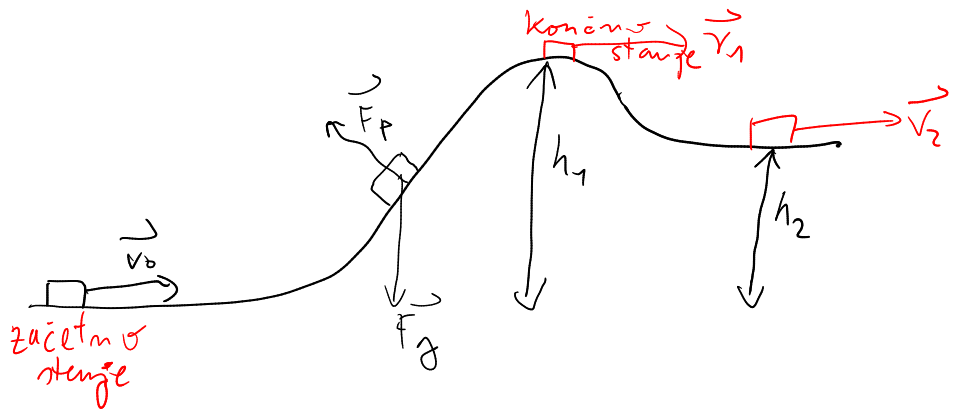
$$h_1 = 1 \text{ m}$$

$$h_2 = 0.6 \text{ m}$$

$$v_1 = ?$$

$$v_2 = ?$$

$$h_{\text{max}} = ?$$



$$\Delta W = A'$$

$$\Delta W_k + \Delta W_p + \Delta W_{\text{pr}} = A'$$

$$\vec{F}_p \cdot d\vec{s} = 0$$

$$W_k = \frac{1}{2} m v^2$$

$$W_p = m g h$$

$$W_{\text{pr}} = \frac{1}{2} k \Delta x^2$$

$$A = F_s$$

$$A = \vec{F} \cdot \vec{s}$$

$$A = \int \vec{F} \cdot d\vec{s}$$

$$\Delta W_k + \Delta W_p = 0$$

$$\left( \frac{1}{2} m v^2 - \frac{1}{2} m v_0^2 \right) + m g h_1 = 0$$

$$v_1 = \sqrt{v_0^2 - 2 g h_1} =$$

$$\sqrt{(5 \text{ m/s})^2 - 2 \cdot 10 \frac{\text{m}}{\text{s}^2} \cdot 1 \text{ m}} = 2.32 \frac{\text{m}}{\text{s}}$$

$$v_2 = \sqrt{v_0^2 - 2 g h_2} = \sqrt{(5 \text{ m/s})^2 - 2 \cdot 10 \frac{\text{m}}{\text{s}^2} \cdot 0.6 \text{ m}} = 3.64 \frac{\text{m}}{\text{s}}$$

$$v_1 = 0 = \sqrt{v_0^2 - 2 g h_{\text{max}}} \rightarrow h_{\text{max}} = \frac{v_0^2}{2g} = \frac{(5 \text{ m/s})^2}{2 \cdot 9.81 \text{ m/s}^2} =$$

$$= 1.28 \text{ m}$$