

5.10

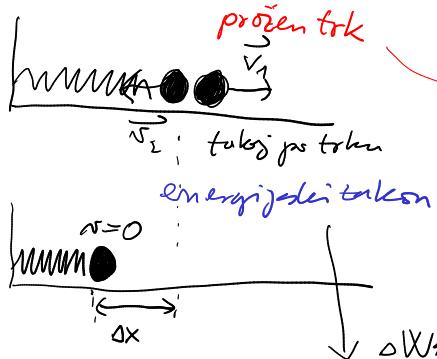


$$\begin{aligned}m_1 &= 50 \text{ g} \\m_2 &= 180 \text{ g} \\v_0 &= 0,8 \text{ m/s} \\k &= 20 \text{ N/m}\end{aligned}$$

$\Delta x = ?$

$$\begin{aligned}\Delta K_2 &= 0 \\K_{2\text{pred}} &= K_{2\text{poz}}\end{aligned}$$

$$\begin{aligned}\Delta \vec{G} &= 0 \\\vec{G}_{\text{pred}} &= \vec{G}_{\text{poz}}\end{aligned}$$



$$v_2 = ?$$

$$\Delta x = ?$$

$$\Delta K_2 + K_{\text{pr}} = 0$$

$$-\frac{1}{2} m_2 v_2^2 + \frac{1}{2} k \Delta x^2 = 0$$

$$\Delta x = \sqrt{\frac{m_2}{k}} v_2$$

$$\Delta x = \sqrt{\frac{m_2}{k}} \cdot \frac{2 m_1 v_0}{m_1 + m_2} =$$

$$= \sqrt{\frac{0,18 \text{ kg}}{20 \text{ N/m}}} \cdot \frac{2 \cdot 50 \text{ g}}{230 \text{ g}} \cdot 0,8 \text{ m/s} =$$

$$= 0,033 \text{ m}$$

$$\left. \begin{aligned}m_1 v_0^2 &= \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 \\m_1 v_0 &= m_1 v_1 + m_2 v_2\end{aligned} \right\} v_2 = ?$$

$$v_1 = v_0 - \frac{m_2}{m_1} v_2$$

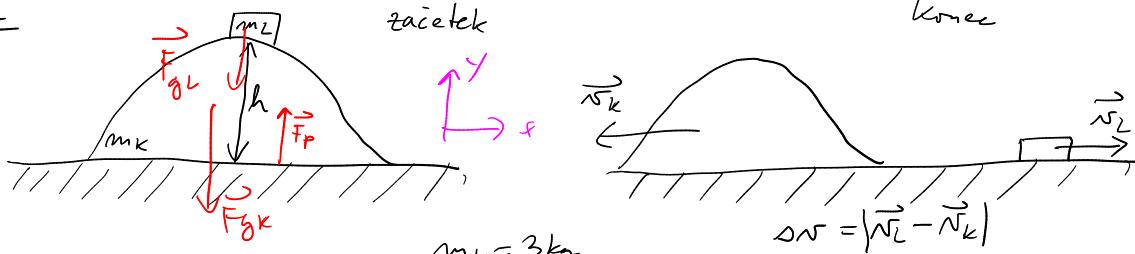
$$m_1 v_0^2 = m_1 \left(v_0 - \frac{m_2}{m_1} v_2 \right)^2 + m_2 v_2^2$$

$$\begin{aligned}m_1 v_0^2 &= m_1 v_0^2 - 2 m_2 v_0 v_2 + \\&+ \frac{m_2^2}{m_1} v_2^2 + m_2 v_2^2\end{aligned}$$

$$0 = -2 m_2 v_0 + \frac{m_2}{m_1} v_2 + v_2$$

$$v_2 = \frac{2 v_0}{1 + \frac{m_2}{m_1}} = \frac{2 m_1 v_0}{m_1 + m_2}$$

5.12



$$\begin{aligned}m_K &= 3 \text{ kg} \\m_L &= 1 \text{ kg} \\\Delta v &= 4 \text{ m/s} \\h &=?\end{aligned}$$

$$\Delta v = \sqrt{v_L^2 - v_K^2}$$

$$\Delta W = \Delta W_F + \Delta W_P = 0$$

$$\Delta \vec{G} = \int \vec{F} \cdot dt \rightarrow \text{X: } \Delta G_x = \int F_x dt = 0$$

$$\frac{1}{2} m_K v_K^2 + \frac{1}{2} m_L v_L^2 - m_L g h = 0$$

$$(m_L v_L + m_K v_K) - 0 = 0$$

$$v_K = -\frac{m_L}{m_K} v_L$$

$$\Delta v = v_L - v_K$$

$$\Delta v = v_L \left(1 + \frac{m_L}{m_K}\right)$$

$$\frac{1}{2} m_K \left(-\frac{m_L}{m_K} v_L\right)^2 + \frac{1}{2} m_L v_L^2 = m_L g h$$

$$\frac{1}{2} \frac{m_L^2}{m_K} v_L^2 + \frac{1}{2} m_L v_L^2 = m_L g h$$

$$\frac{1}{2} \left(\frac{m_L}{m_K} + 1\right) v_L^2 = g h \rightarrow$$

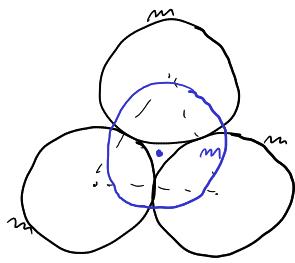
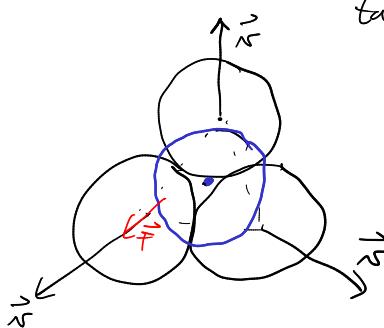
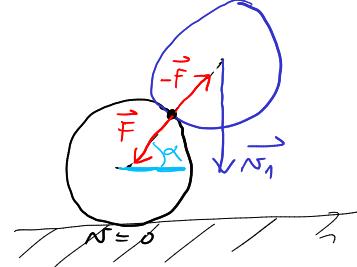
$$v_L = \sqrt{\frac{2 g h}{1 + \frac{m_L}{m_K}}} = \sqrt{\frac{2 m_K g h}{m_L + m_K}}$$

$$\Delta v = \sqrt{\frac{2 m_K g h}{m_L + m_K}} \cdot \sqrt{\frac{(m_L + m_K)}{(m_K)^2}} = \sqrt{\frac{2(m_L + m_K) g h}{m_K}}$$

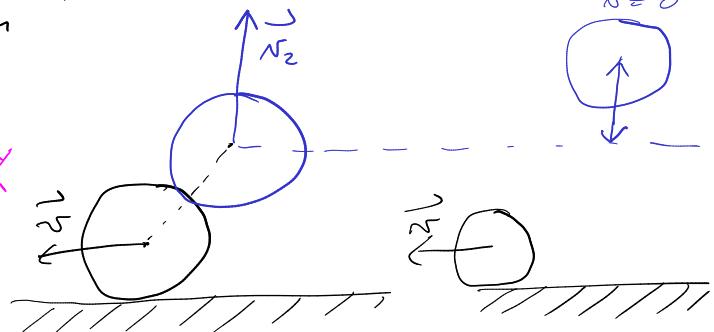
$$h = \frac{m_K \Delta v^2}{2(m_K + m_L) g} = \frac{3 \text{ kg} \cdot 16 \text{ m}^2/\text{s}^2}{8 \cdot 2 \cdot 4 \text{ kg} \cdot 10 \text{ m}} = \underline{\underline{0,6 \text{ m}}}$$

5.19

$$\begin{aligned} N_2 &=? \\ v &= 2 \text{ m/s} \end{aligned}$$

tik pred
etkom

takoj po trku



$$W_k^{\text{pred}} = W_2^{\text{po}} \rightarrow \frac{1}{2} m v_1^2 = \frac{1}{2} m v_2^2 + 3 \cdot \frac{1}{2} m v^2$$

$$v_1^2 = v_2^2 + 3v^2$$

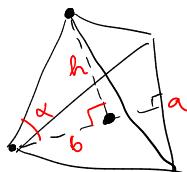
$$\text{črna krogica: } x: G_x^{\text{po}} - G_x^{\text{pred}} = \int F_x dt$$

$$m v \cos \alpha - 0 = \int F_{\text{cos} \alpha} dt = \cos \alpha \int F dt$$

$$\text{modra krogica: } y: G_y^{\text{po}} - G_y^{\text{pred}} = \int F_y dt$$

$$(m v_2 - m v_1) = 3 \int F_{\text{sin} \alpha} dt = 3 \sin \alpha \int F dt$$

$$\frac{v_2 - v_1}{v} = 3 \tan \alpha = 3\sqrt{2}$$



$$\tan \alpha = \frac{h}{b}$$

$$b = \frac{a\sqrt{3}}{2} \cdot \frac{2}{3} = \frac{a}{\sqrt{3}}$$

$$b^2 + h^2 = a^2$$

$$h = \sqrt{a^2 - b^2} = \sqrt{a^2 - \frac{a^2}{3}} = \sqrt{\frac{2a^2}{3}} = a\sqrt{\frac{2}{3}}$$

$$\tan \alpha = \frac{a\sqrt{\frac{2}{3}}}{a/\sqrt{3}} = \sqrt{2}$$

$$\begin{aligned} v_1^2 &= v_2^2 + 3v^2 \\ v_2 &= v_1 + 3\sqrt{2}v \end{aligned}$$

$$v_1^2 = (v_1 + 3\sqrt{2}v)^2 + 3v^2 = v_1^2 + 6\sqrt{2}v_1 v + 18v^2 + 3v^2$$

$$0 = 6\sqrt{2}v_1 v + 21v^2$$

$$v_1 = -\frac{21}{6\sqrt{2}}v = -\frac{7}{2\sqrt{2}}v = -\frac{7}{2\sqrt{2}} \cdot 2 \text{ m/s} = -4,9 \text{ m/s}$$

$$h = ?$$

$$\begin{aligned} \Delta W_2 + \Delta W_p &= 0 \\ -\frac{1}{2}\mu m v_2^2 + \mu m g h &= 0 \end{aligned}$$

(za modro kroglico)

$$h = \frac{v_2^2}{2g}$$

$$h = \frac{v_1^2 - 3v^2}{2g} = \frac{(-4,9 \text{ m/s})^2 - 3(2 \text{ m/s})^2}{2 \cdot 9,81 \text{ m/s}^2} = 0,6 \text{ m}$$

$$v_2^2 = v_1^2 - 3v^2$$

3.33

$$F = m \cdot a$$

$$M = J \cdot \alpha \rightarrow \text{kolmíkovský moment}$$

\downarrow
vzdálenostní moment

$$\nu_0 = 0,3 \text{ Hz}$$

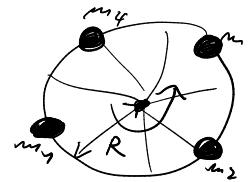
$$M = -100 \text{ Nm}$$

$$J_0 = 500 \text{ kg m}^2$$

$$m_{1,2,3,4} = 25, 30, 35, 40 \text{ kg}$$

$$R = 1,5 \text{ m}$$

$$N = ?$$



$$\omega_k^2 = \omega_e^2 + 2\alpha \cdot \varphi$$

$$\varphi = (2\pi\nu_0)^2 + 2\alpha (2\pi N)$$

$$N = -\frac{\pi\nu_0^2}{\alpha}$$

$$M = (J_0 + m_1 R^2 + m_2 R^2 + m_3 R^2 + m_4 R^2) \alpha$$

$$\alpha = \frac{M}{J_0 + (m_1 + m_2 + m_3 + m_4) R^2}$$

$$N = -\frac{\pi\nu_0^2 (J_0 + (m_1 + m_2 + m_3 + m_4) R^2)}{M} = \frac{\pi 0,3^2 (500 \text{ kg m}^2 + 130 \text{ kg} \cdot 1,5^2 \text{ m}^2)}{8^2 \cdot 100 \text{ Nm}} =$$

$$= \underline{\underline{2,24}}$$

3.35

a)

$$J = \sum_i J_i = \sum_i m_i r_i^2 = 4 \cdot m \cdot \left(\frac{a\sqrt{\Sigma}}{2}\right)^2 = 2ma^2$$

$$J = \int dm \cdot r^2$$

b)

$$J = \int dm \cdot R^2 = R^2 \int dm = R^2 m$$

c)

$$J = \int dm \cdot r^2 = \int_{-l/2}^{l/2} \left(\frac{dx}{l} m \right) \cdot x^2 = \frac{m}{l} \frac{x^3}{3} \Big|_{-l/2}^{l/2} =$$

$$= \frac{m}{3l} \left(\left(\frac{l}{2}\right)^3 - \left(-\frac{l}{2}\right)^3 \right) = \frac{m}{3l} 2 \cdot \frac{l^3}{8} =$$

$$= \frac{1}{12} ml^2$$

d)

$$J = \int dm \cdot r^2 = \int dS \frac{m}{\pi R^2} r^2$$

pozycja kolożyna

pozycja kroża

$$dS = \pi(r+dr)^2 - \pi r^2 =$$

$$= \pi r^2 + 2\pi r dr + dr^2 - \pi r^2 \quad \cancel{\text{zamniejszenie}}$$

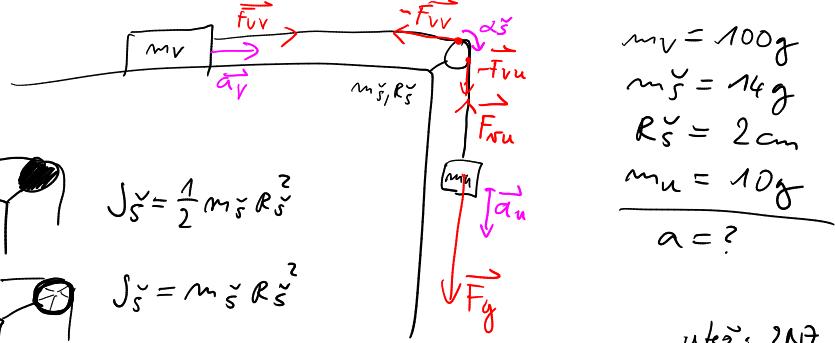
$$dS = 2\pi r dr$$

$$J = \int_0^R \frac{2\pi r dr}{\pi R^2} m r^2 = \frac{2m}{R^2} \int_0^R r^3 dr = \frac{2m}{R^2} \frac{r^4}{4} \Big|_0^R = \frac{2m}{R^2} \frac{R^4}{4} = m \frac{R^2}{2}$$

e)

$$J = \int dm \cdot r^2 = \int dV \frac{m}{\pi R^2 h} \cdot r^2 = \int_0^R \frac{2\pi r dr h}{\pi R^2 h} m r^2 = \frac{1}{2} m R^2$$

$$dV = 2\pi r dr \cdot h$$



- a)
 $J_s^v = \frac{1}{2} m_s R_s^2$
- b)
 $J_s^v = m_s R_s^2$
- c)
 $J_s^v = 0$
 $m_s^v = 0$

$$(\vec{F}_{vr} | + | \vec{F}_{ru})$$

$$\alpha = |\vec{a}_u| = |\vec{a}_v| = \alpha_T = \alpha_s R_s$$

unter 2Nz $m_u g - F_{ru} = m_u a$

vor 2Nz $\vec{F}_{nv} = m_u a$

Skript: $\sum \vec{\tau} = J \ddot{\alpha}$ $\vec{M} = \vec{r} \times \vec{F}$

$$\vec{\tau} = \vec{r}_u \times (-\vec{F}_{ru}) + \vec{r}_s \times (-\vec{F}_{nv})$$

$$|\vec{\tau}| = R_s F_{ru} - R_u F_{nv}$$

$$R_s (F_{ru} - F_{nv}) = J_s^v \cdot \alpha_s^v$$

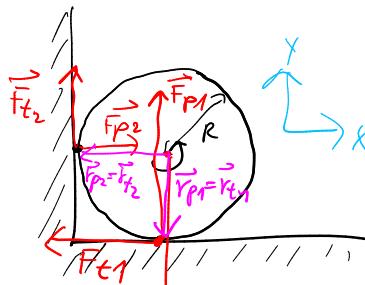
$$R_s (m_u (g - a) - m_v a) = J_s^v \cdot \frac{a}{R_s}$$

$$a (m_u + m_v + \frac{J_s^v}{R_s^2}) = m_u g$$

$$a = \frac{m_u g}{m_u + m_v + \frac{J_s^v}{R_s^2}} = \frac{m_u g}{m_u + m_v + m_s \cdot \begin{cases} 1 \\ 0 \end{cases}}$$

$$a = 9,81 \frac{\text{m}}{\text{s}^2} \cdot \frac{10}{10 + 100 + \begin{cases} 7 \\ 0 \end{cases}} = \begin{cases} \text{a)} 0,84 \\ \text{b)} 0,79 \\ \text{c)} 0,89 \end{cases} \frac{\text{m}}{\text{s}^2}$$

3.38



$$\nu_0 = 10,1 \text{ Hz} \quad \omega_t = 0,1$$

$$R = 10 \text{ cm}$$

$$N = ?$$

$$N = -\frac{\pi \nu_0^2}{\alpha}$$

$$\sum \vec{\tau} = J \vec{\alpha}$$

$$\vec{\tau}_g + \vec{r}_{p1} \times \vec{F}_{p1} + \vec{r}_{t1} \times \vec{F}_{t1} + \cancel{\vec{r}_{p2} \times \vec{F}_{p2}} + \cancel{\vec{r}_{t2} \times \vec{F}_{t2}}$$

$$\vec{\tau}_g = 0 \quad \vec{r}_{p1} \parallel \vec{F}_{p1}$$

$$\vec{r}_{p2} \parallel \vec{F}_{p2}$$

$$M = -R(F_{t1} + F_{t2}) = \frac{1}{2} m R^2 \cdot \alpha$$

$$\alpha = -\frac{2(F_{t1} + F_{t2})}{m R}$$

$$2N2: \sum \vec{F} = m \vec{a}^* = 0$$

$$\vec{F}_g + \vec{F}_{p1} + \vec{F}_{t1} + \vec{F}_{p2} + \vec{F}_{t2} = 0$$

$$\alpha = \frac{-2g}{R} \frac{\omega_t + k_t^2}{1 + \omega_t^2}$$

$$X: -F_{t1} + F_{p2} = 0 \quad F_{t1} = k_t F_{p1}$$

$$Y: -mg + F_{p1} + F_{t2} = 0 \quad F_{t2} = k_t F_{p2}$$

$$-F_{t1} + \frac{F_{t2}}{k_t} = 0 \rightarrow F_{t1} = \frac{F_{t2}}{k_t}$$

$$\frac{F_{t1}}{k_t} + F_{t2} = mg \rightarrow \frac{F_{t2}}{k_t^2} + F_{t2} = mg \rightarrow F_{t2} = \frac{mg}{1 + \frac{1}{k_t^2}} = \frac{k_t^2 mg}{1 + k_t^2}$$

$$N = -\frac{\pi \nu_0^2}{\alpha} = \frac{\pi \nu_0^2 R}{2g} \frac{1 + \omega_t^2}{1 + k_t^2} = \frac{\pi \cdot 10,1^2 \cdot 0,1}{2,8^2 \cdot 9,81} \cdot \frac{1,01}{0,11} = \underline{15}$$