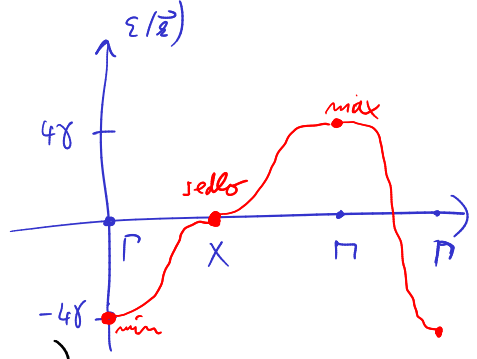
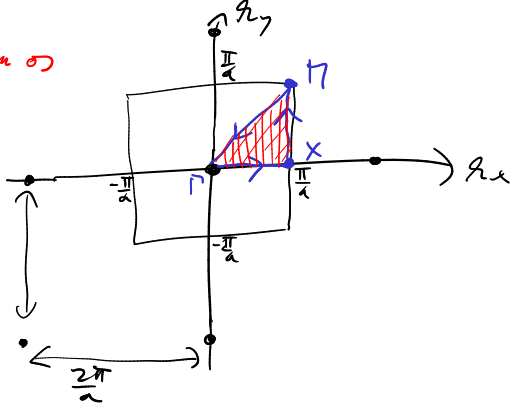
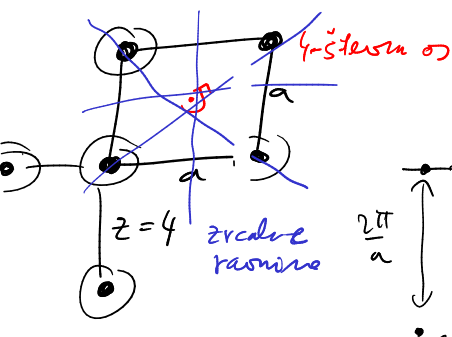


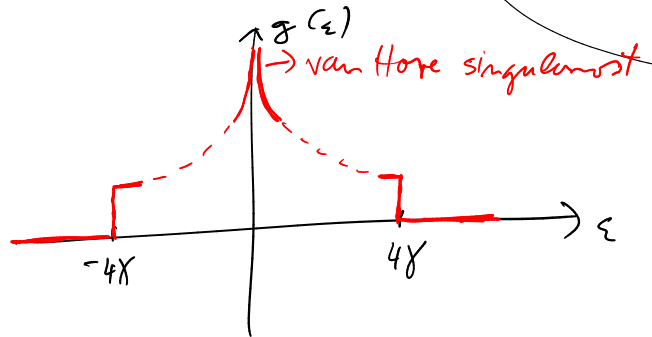
V približku teorezi zračunaj gostoto stanj za pos, ki nastane iz s-orbital atomov na kvadratni mreži



$$\epsilon(\vec{k}) = E_0 - \gamma \sum_{\vec{R}=n.s.\phi} e^{i\vec{k}\cdot\vec{R}} = -2\gamma(\cos k_x a + \cos k_y a)$$

- $\vec{R} = (a, 0)$
- $(-a, 0)$
- $(0, a)$
- $(0, -a)$

- $\Gamma = (0, 0) \quad \epsilon(\Gamma) = -4\gamma \text{ min}$
- $X = (\frac{\pi}{a}, 0) \quad \epsilon(X) = 0$
- $\Pi = (\frac{\pi}{a}, \frac{\pi}{a}) \quad \epsilon(\Pi) = 4\gamma \text{ max}$



simetrije:

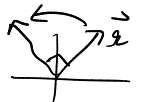
$$\epsilon(\vec{k}) = -\gamma \sum_{\vec{R}=n.s.\phi} e^{i\vec{k}\cdot\vec{R}}$$

S simetrijsko operacijo iz simetrijske grupe kvadratne Bravaisove mreže

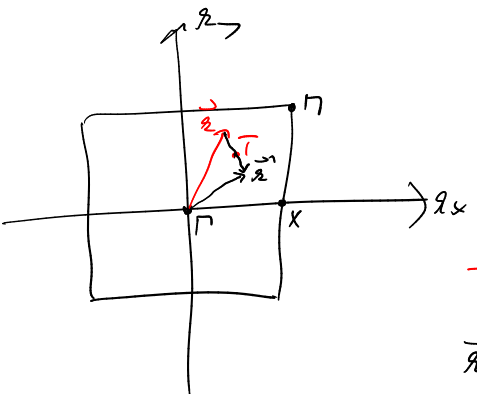
$$\{\vec{R}=n.s.\phi\} = \{S\vec{R}=n.s.\phi\}$$

$$\begin{aligned} \epsilon(\vec{k}) &= -\gamma \sum_{\vec{R}=n.s.\phi} e^{i\vec{k}\cdot S\vec{R}} = -\gamma \sum_{\vec{R}=n.s.\phi} e^{i(S^{-1}\vec{k})\cdot\vec{R}} \\ &= -\gamma \sum_{\vec{R}=n.s.\phi} e^{i(S^{-1}\vec{k})\cdot\vec{R}} = \epsilon(S^{-1}\vec{k}) \end{aligned}$$

rotacija za 90°: $\vec{k} = (k_x, k_y) \rightarrow (-k_y, k_x)$



$$\begin{aligned} \epsilon(-k_y, k_x) &= -2\gamma(\cos(-k_y a) + \cos k_x a) = \\ &= -2\gamma(\cos k_y a + \cos k_x a) = \epsilon(k_x, k_y) \end{aligned}$$



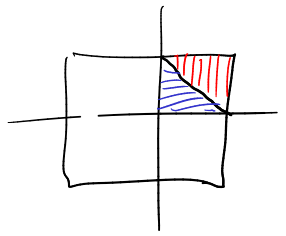
- Γ : min
- Π : max
- X : saddle

$$T = (\frac{\pi}{2a}, \frac{\pi}{2a})$$

$$\vec{k}' = T - (\vec{k} - T) = 2T - \vec{k}$$

$$\epsilon(\vec{k}') = \epsilon(\frac{\pi}{2a} k_x, \frac{\pi}{2a} - k_y) = -2\gamma(-\cos k_x a - \cos k_y a) = -\epsilon(\vec{k})$$

$\hookrightarrow g(\epsilon) = g(-\epsilon)$ gostota stanj je sodna funkcija ϵ

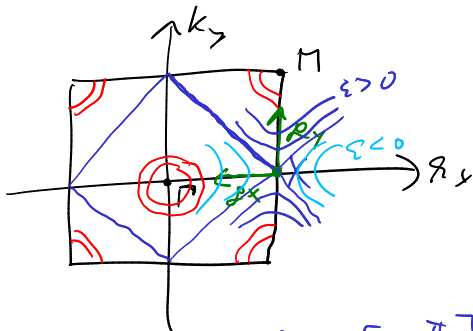


$$\varepsilon(\vec{z}) = -2\gamma (\cos z_x a + \cos z_y a)$$

$$\Gamma = (0,0)$$

$$\vec{z} = \Gamma + \vec{\rho} \quad |\vec{\rho}| < \frac{\pi}{a} \quad \varepsilon(\vec{\rho}) = -4\gamma + \gamma \rho^2 a^2 = -4\gamma + \frac{\hbar^2 \rho^2}{2m a^2} \quad m^* = \frac{\hbar^2}{2\gamma a^2}$$

$$g(\varepsilon) = \text{konst} \cdot \Theta(\varepsilon + 4\gamma)$$



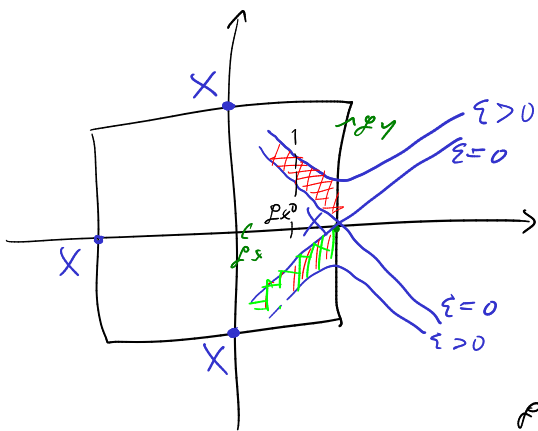
$$X: \vec{z} = (z_x, \frac{\pi}{a} - z_x) \quad z_x \in [0, \frac{\pi}{a}]$$

$$\varepsilon(\vec{z}) = -2\gamma (\cos \frac{z_x}{a} + \cos (\frac{\pi}{a} - z_x) a) = 0$$

$$X = (\frac{\pi}{a}, 0) \quad (z_x, z_y) \rightarrow (\frac{\pi}{a} - z_x, z_y)$$

$$\vec{z} = X + \vec{\rho} \quad |\vec{\rho}| < \frac{\pi}{a}$$

$$\varepsilon(\vec{z}) = -2\gamma (\cos (\frac{\pi}{a} - \rho_x) a + \cos \rho_y a) = -2\gamma (-\cos \rho_x a + \cos \rho_y a) = \gamma a^2 (-\rho_x^2 + \rho_y^2)$$



$$g(\varepsilon) = \frac{1}{V} \frac{N(\varepsilon, \varepsilon + d\varepsilon)}{d\varepsilon} = \frac{1}{V} \frac{dN(0, \varepsilon)}{d\varepsilon}$$

$$N(0, \varepsilon) = 2 \cdot 4 \cdot 2 \cdot \int_0^{\rho_x^0} d\rho_x \left(\sqrt{\frac{\varepsilon}{\gamma a^2} + \rho_x^2} - \rho_x \right) = \frac{(2\pi)^2}{L^2}$$

= # 4 sollen spin

$$= \frac{4L^2}{\pi^2} \int_0^{\rho_x^0} \left(\sqrt{\frac{\varepsilon}{\gamma a^2} + \rho_x^2} - \rho_x \right) d\rho_x$$

$$g(\varepsilon) = \frac{4}{\pi^2} \frac{d}{d\varepsilon} \int_0^{\rho_x^0} \left(\sqrt{\frac{\varepsilon}{\gamma a^2} + \rho_x^2} - \rho_x \right) d\rho_x = \int \frac{dx}{\sqrt{a^2 + x^2}} = \text{arsh} \frac{x}{a}$$

$$= \frac{4}{\pi^2} \int_0^{\rho_x^0} \frac{1}{2\sqrt{\frac{\varepsilon}{\gamma a^2} + \rho_x^2}} \cdot \frac{1}{\gamma a^2} d\rho_x = \frac{2}{\pi^2 \gamma a^2} \int_0^{\rho_x^0} \frac{d\rho_x}{\sqrt{\frac{\varepsilon}{\gamma a^2} + \rho_x^2}} = \frac{2}{\pi^2 \gamma a^2} \text{arsh} \left(\rho_x^0 \sqrt{\frac{\gamma a^2}{\varepsilon}} \right)$$

$$g(\varepsilon \rightarrow 0) \rightarrow g(\varepsilon) = \frac{2}{\pi \gamma a^2} \ln \left(2 \rho_x^0 \sqrt{\frac{\gamma a^2}{\varepsilon}} \right) = \frac{2}{\pi \gamma a^2} \left(\ln 2 \rho_x^0 \sqrt{\gamma a^2} - \frac{1}{2} \ln \varepsilon \right)$$

↑ konst
↑ divergiert
Zusammenfassen

$$g(\varepsilon) = -\frac{1}{\pi \gamma a^2} \ln \varepsilon \propto -\ln \varepsilon$$

$\text{arsh}(u \gg 1) \approx \ln(2u)$
 $\text{sh} x = y \quad y \gg 1$
 $\frac{e^x}{2} = y$
 $x = \ln(2y)$